

# WL-21008 MASTER-D1



# DESCRIPTION

The Master-D1 is a digital position computing board. It calculates the position of any Locator relative to the position of the Receivers, as well as global position through use of the integrated GPS and IMU.

The board supports up to 7 independent D1 devices and 1 A1 devices. It is accessed through a network interface. The Master-D1 is running its own webserver which exposes an API and a GUI.

With its small physical footprint, the board is easily integrated into a topside housing.

### BENEFITS

- Extremely small footprint enabling easy integration in other equipment.
- Highly robust operation in areas with reflections (shallow water, around installations etc.)

### CONTENTS

Master-D1 board

# FAMILY

The Master-D1 is part of the Water Linked Underwater GPS System.

#### WL-21005 RECEIVER-D1

The Receiver-D1 is a digital hydro acoustic receiver that is designed to receive the signal



from a Water Linked Locator. The Receiver-D1 is connected to the Master-D1 using a cable. A minimum of 3 Receiver-D1s are required to get the position of a Locator-D1.

#### WL-21009 LOCATOR-A1 / WL-21016 LOCATOR-D1

The Locator-A1/D1 are hydro acoustic locator devices that transmits acoustic waves which the Receiver-D1s will receive. The



Locator-A1/D1 is connected to the Master-D1 using a cable.



#### **MECHANICAL**

Length	: 154 mm
Width	: 70 mm
Thickness	: 31 mm
Operating temperature	: -10 to +60 °C

# **ELECTRICAL**

Input voltage	: 10-18 V
Input current	: 400 mA

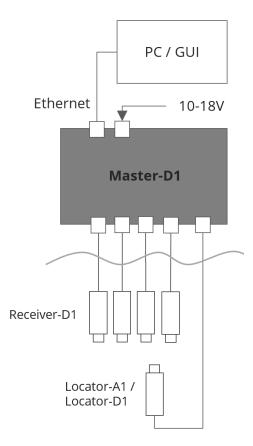
### **INTERFACES**

D1 Interfaces	: 7
D1 connector:	: JST BM06B-GHS-TBT
A1 Interfaces	: 1
A1 connector:	: JST BM03B-GHS-TBT
Ethernet interfaces	: 1 (10/100/1000BASE-X)
Ethernet connector	: RJ45
Power connector	: Molex Micro-Fit 3mm

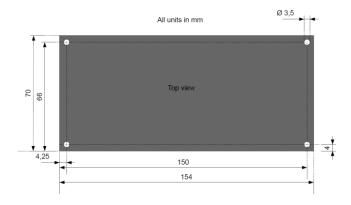
# **APPROVALS**

**RoHS** compliant CE

# **BLOCK DIAGRAM**



# DIMENSIONS





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Water Linked AS Stiklestadveien 1 N-7041 TRONDHEIM, NORWAY

Phone +47 90115038 E-Mail: info@waterlinked.com



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